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Name: Tony Feng Email/Phone: tonyfeng@stanford.edu

Speaker's Name: Emanuele Macri

Talk Title: Derived categories of cubic fourfolds and non-commutative K3 surfaces

Date: 2 / 8 / 19 Time: 11 : 00 am / pm (circle one)

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MODULI OF OBJECTS IN KUZNETSOV COMPONENTS

EMANUELE MACRI

1. KUZNETSOV COMPONENTS

This is joint work with Bayer, Lahoz, Nuer, Perry, Stellari.

Let X be smooth projective over \mathbf{C} . We look at $D^b(X) := D^b(\text{Coh}(X))$. A *Kuznetsov component* is a certain admissible (triangulated) subcategory $\mathcal{D} \subset D^b(X)$. We ask for an adjoint p to the inclusion $\mathcal{D} \hookrightarrow D^b(X)$. The goal is to understand these categories by studying their moduli space of objects.

1.1. Motivation.

- The first motivation is speculative: we believe that these is related to rationality. More precisely, the \mathcal{D} might provide an interesting birational invariant.
- Many geometric constructions on X can be realized as moduli spaces on \mathcal{D} .

Example 1.1. Let X be a surface. Then we have the following conjecture.

Conjecture 1.2 (Orlov). *X is rational if and only if $D^b(X)$ has a “full exceptional collection”, meaning it can be decomposed into pieces which are derived categories of points.*

Moduli spaces of objects in these components are not interesting in this case (being zero-dimensional), but the existence is fundamental in studying properties for all moduli spaces of sheaves on such surfaces.

Example 1.3. Let X be a Fano 3-fold, $\rho(X) = 1$, $i(X) = 2$.

Let $\mathcal{D}_X := \langle \mathcal{O}_X, \mathcal{O}_X(1) \rangle^\perp$, meaning the subcategory of objects C such that $\text{Ext}^*(\mathcal{O}_X, C) = \text{Ext}^*(\mathcal{O}_X(1), C) = 0$.

Then X is rational if and only if \mathcal{D}_X is “geometric”, i.e. $\mathcal{D}_X \cong D^b(\text{curve})$ or it has a full exceptional collection. (Unfortunately, at the moment the proof is indirect. You find two lists of objects satisfying the respective properties, and verify that they coincide.)

Given $\ell \subset X$, with ideal sheaf \mathcal{I}_ℓ , associate $p(\mathcal{I}_\ell) \in \mathcal{D}_X$ where p is the projection left adjoint to $\mathcal{D}_X \hookrightarrow D^b(X)$. This shows that the moduli space of lines is already “a moduli space in \mathcal{D}_X ”, which means \mathcal{D}_X is uninteresting for this purpose.

Let X be a cubic 3-fold. Then from a moduli perspective $p(\kappa(x))$ (the projection of the skyscraper sheaf) looks better once you project to \mathcal{D}_X . It is the resolution of the blowup of the theta divisor.

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Example 1.4. Let X be a cubic 4-fold, and define

$$\mathcal{D}_X = \langle \mathcal{O}_X, \mathcal{O}_X(1), \mathcal{O}_X(2) \rangle^\perp.$$

The expectation is that rationality of X should have something to do with \mathcal{D}_X be geometric, and more precisely that $\mathcal{D}_X \cong D^b(\mathbf{K}3)$.

The moduli spaces are interesting. For a line $\ell \subset X$, $p(\mathcal{I}_\ell)$ has the same deformation space as the moduli space (i.e. Hilbert scheme) of lines.

On the other hand, the moduli space of $\kappa(x)$ has more deformations – the associated moduli space contains X .

2. MODULI SPACES IN \mathcal{D}_X

2.1. Cohomology.

Example 2.1. Let X be a cubic 4-fold. We form the Kuznetsov component \mathcal{D}_X as before. Properties:

- (1) Serre duality: for all $E, F \in \mathcal{D}_X$, we have $\mathrm{Ext}^*(E, F) = \mathrm{Ext}^{2-*}(F, E)^\vee$. (This suggests that \mathcal{D}_X is “smooth”.)
- (2) $H(\mathcal{D}_X; \mathbf{Z}) = K_{\mathrm{top}}(\mathcal{D}_X)$. This is a lattice $U^4 \oplus E_8(-1)^2$, which looks like $H^*(\mathbf{K}3; \mathbf{Z})$. It has a weight 2 Hodge structure (e.g. from Hochschild cohomology).
- (3) There is a Mukai vector $v: K(\mathcal{D}_X) \rightarrow H_{\mathrm{Hdg}}(\mathcal{D}_X; \mathbf{Z})$ given by “ $v = \mathrm{ch} \cdot \mathrm{Td}$ ”. We have $\chi(E, F) = -(v(E), v(F))$ where χ is the Euler characteristic.

In general, the structure we fix is $\mathcal{D}_X \subset D^b(X)$ with left adjoint p , and $v: K_0(\mathcal{D}_X) \rightarrow \Lambda$ where Λ is a finite rank abelian group.

2.2. Stability. We need an abstract notion of stability in derived categories in order to define moduli spaces.

Example 2.2. Let $X = Q_1 \cap Q_2 \subset \mathbf{P}^5$. Then we get $\mathcal{D}_X \cong D^b(C)$ where C is a genus 2 curve. In this case we want “stability” to mean Mumford stability for coherent sheaves on C .

Definition 2.3 (Bridgeland, Kontsevich-Soibelman). A *stability condition* on \mathcal{D}_X is a pair $\sigma = (Z, \mathcal{A})$ where

- $Z: \Lambda \rightarrow \mathbf{C}$,
- \mathcal{A} is the heart of a t -structure

such that

- (1) $Z(v(\mathcal{A} - 0)) \subset \mathbf{H} \cup \mathbf{R}_{<0}$. We define $\mu_\sigma = -\frac{\mathrm{Re} z}{\mathrm{Im} z}$ to be the “slope”. We say $E \in \mathcal{A}$ is σ -semistable if for all $F \subset E$, $\mu(F) \leq \mu(E)$.
- (2) Harder-Narasimhan filtrations exist.
- (3) We want a kind of discreteness of semistable objects. To codify this, we ask for a quadratic form Q on $\Lambda_{\mathbf{R}}$ such that $Q|_{\ker Z} < 0$.
- (4) Semistable objects of fixed Mukai vector v_0 satisfy universal openness and boundedness.

Example 2.4. In the previous example, $\mathcal{A} = \mathrm{Coh}(C)$ and $Z = -\mathrm{deg} + i \mathrm{rank}$.

2.3. Existence of moduli spaces.

Theorem 2.5.

- (1) (Bridgeland) The set of stability conditions $\text{Stab}(\mathcal{D}_X)$ has the structure of a complex manifold with dimension being $\text{rank } \Lambda$.
- (2) Fix $\sigma \in \text{Stab}(\mathcal{D}_X)$ and $v_0 \in \Lambda$. Then $M_\sigma(v_0)$ exists as an Artin stack of finite type over \mathbf{C} [Lieblich-Toda]. It has a good moduli space [Alper, Halpern-Leistner, Heinloth] which is a proper and separated algebraic space [Abramovich-Polishchuk].
There is a canonical line bundle $\ell_\sigma(v_0)$ on this good moduli space, which is a strictly nef real divisor class [BM].
- (3) (BLMS) If X is a Fano 3-fold or cubic 4-fold, then there is a Kuznetsov component \mathcal{D}_X with $\text{Stab}(\mathcal{D}_X) \neq \emptyset$.

3. RELATIVE STABILITY

We now want to extend this notion to families. Issues: we want to be able to do semistable reduction, we want to deform, and we want the moduli space to be proper.

Consider a smooth projective family $\mathcal{X} \rightarrow S$. We will want a subcategory $\mathcal{D}_{\mathcal{X}/S} \subset D^b(\mathcal{X})$ which is S -linear, meaning it's preserved by $D_{\text{perf}}(S)$.

We want to have a notion of stability varying in fibers. This is subtle, but we finally found a definition that seems to work. To begin, we want a family of functions $v_s: K_{\text{num}}(\mathcal{D}_S) \rightarrow \Lambda$ for $s \in S$, which are constant over S .

Definition 3.1 (BLMNPS). A collection $\underline{\sigma} = \{\sigma_s = (Z_s, \mathcal{A}_s)\}_{s \in S}$ of stability conditions is a *stability condition on $\mathcal{D}_{\mathcal{X}/S}$ over S* if

- (1) Z_S is locally constant, hence we get $Z: \Lambda \rightarrow \mathbf{C}$.
- (2) Universal open-ness of stability.
- (3) For all smooth curves $C \rightarrow S$, the collection $\{\sigma_c\}$ “integrates” over C . This means we want a global heart, and for the stability conditions to be induced by global HN filtrations and stability on this heart.
- (4) A uniform Q .
- (5) Boundedness.

Theorem 3.2. (1) $\text{Stab } \mathcal{D}_{\mathcal{X}/S}$ is a manifold.

- (2) $M_{\underline{\sigma}}(v_0) \rightarrow S$ exists and has a good moduli space which is proper and separated over S .
- (3) If $\mathcal{X} \rightarrow S$ is a smooth family of Fano 3-folds or cubic 3-folds, then the Kuznetsov component $\mathcal{D}_{\mathcal{X}/S}$ has $\text{Stab}(\mathcal{D}_{\mathcal{X}/S}) \neq \emptyset$.

Remark 3.3. Λ is “not constant”. Assume \underline{v} factors through $\mathcal{N}(\mathcal{D}_{\mathcal{X}/S})$. Then $\ell_{\underline{\sigma}}(\underline{v})$ exists and is strictly S -nef.

4. APPLICATIONS

Let X be a cubic 4-fold. Then we have defined \mathcal{D}_X .

Corollary 4.1. *Fix a primitive vector $v_0 \in H_{\text{Hdg}}(\mathcal{D}_X; \mathbf{Z})$. Let $\sigma \in \text{Stab}(\mathcal{D}_X)$ is generic with respect to v_0 . Then $M_\sigma(v_0) \neq \emptyset$ if and only if $v_0^2 \geq -2$. In such a case $M_\sigma(v_0)$ is smooth projective deformation equivalent to the Hilbert scheme of a K3 surface of dimension $v_0^2 + 2$ with $\ell_\sigma(v_0)$ ample.*

We consider a relative situation over a curve. We need to prove the relative moduli space is smooth. If it's not smooth, one needs to "increase" Λ . This lets one deform to the case of the K3 surface, which we know.